Publications

Skills	Computer Skills: Python, Matlab, C++, TensorFlow, PyTorch, Linux, AWS, SQL, Mongo Languages: Fluent in English and Arabic.
Experience	 Graduate Student Researcher UC Berkeley (May 2017 - December 2022) Developed an open-source framework for running deep reinforcement learning experiments in traffic microscopic simulators, see: https://github.com/flow-project/flow. Conducted computational studies validating the efficacy of reinforcement learning techniques in generating meaningful and diverse control strategies for automated vehicles. Designed, implemented, and tested hierarchical reinforcement learning algorithms for traffic control and robotics problems, see: https://github.com/AboudyKreidieh/h-baselines.
	 Research Intern, Smart City AI Nissan Alliance SV Lab (September 2021 - December 2021) Designed a framework for macroscopic traffic state estimation via connected vehicles. Implemented various traffic state estimators and conducted hyperparameter studies on these estimators to determine the effect of certain features on key performance indicators. Created visualization tools for monitoring the aggregate state of traffic in real-time.
	 Intern - Connected Vehicle Research Toyota InfoTech Labs (June 2021 - August 2021) Developed a lightweight tool for validating the performance of different lane assignment strategies in simulations of throughout-restricted traffic. Formulated and implemented a multi-level hierarchical control mechanism for cooperative lane change assistance across multiple traffic segments.
	 Visiting Student Researcher Glaser Lab, UC Berkeley (May 2015 - August 2015) Collaborated with a team on designing a communication protocol for wireless, system-level communication of sensors in the Sierra Nevada. Programmed an earthquake simulator with LabVIEW to perform position/force PID control tasks and prevent failures and faults.
Teaching	 Course: Deep multi-agent reinforcement learning with applications to autonomous traffic (Aug-Dec 2018) Developed the course curriculum and prepared homework problems in TensorFlow. Provided lectures on various topics in multiagent RL, including non-stationary, communication, and its connections to hierarchical RL. Supervised and guided students through their semester-long projects.
	 Course: Introduction to Computer Programming for Scientists and Engineers (Jan-May 2017) Led lab sessions consisting of around 20 students and mentored them through their development. Formulated homework and exam problems in Matlab.
Selected	Flow: A Modular Learning Framework for Mixed Autonomy Traffic. <i>IEEE Transactions on Robotics</i> (2021).

Inter-Level Cooperation in Hierarchical Reinforcement Learning. arXiv preprint arXiv:1912.02368 (2019). Emergent Behaviors in Mixed-Autonomy Traffic. Conference on Robot Learning (2017).

- AWARDS AND AWS Machine Learning Research Award (2017, 2019) Achievements **2019 Summer Fellow** UC Berkeley, CEE Department (April 2019) Outstanding Graduate Student Award UC Berkeley, Institute of Transportation Studies (December 2018) Siemens Future Makers Challenge Placed 3rd (April 2018) Jane Lewis Fellowship UC Berkeley, Graduate Division (Fall 2016 - Spring 2017) Dean's Honor List Faculty of Engineering and Architecture, AUB (2012 - 2016)
- VOLUNTEER **STEM Outreach Visit** (July 2019)
- Work

• Prepared and hosted a tour of four research labs within UC Berkeley to a group of high school students.

Lebanese Red Cross, Youth Department (August 2011 - March 2013)

- Assisted with workshops in schools, environmental awareness projects, and various other activities.
- Organized the center's inventory and prepared an inventory list.